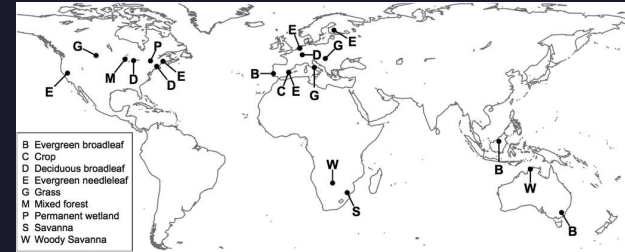
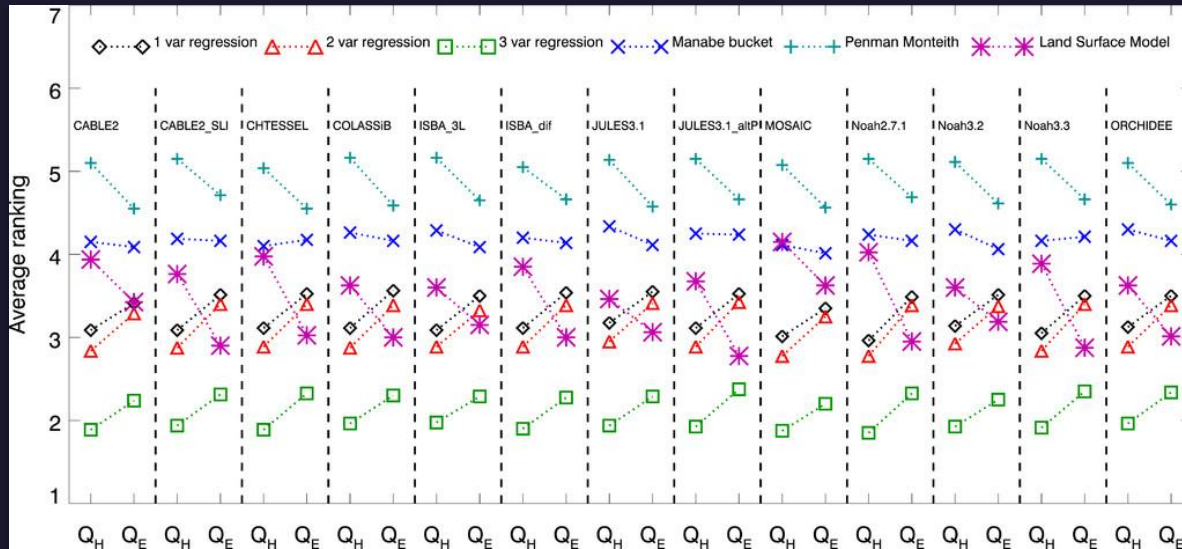
The background of the slide features a complex network of white nodes and connecting lines, set against a vibrant gradient background that transitions from a bright orange-yellow glow on the left to a deep purple on the right. The nodes vary in size and are interconnected by thin white lines, creating a web-like structure. The overall aesthetic is modern and technological.

Models, Hypothesis Testing, & Machine Learning

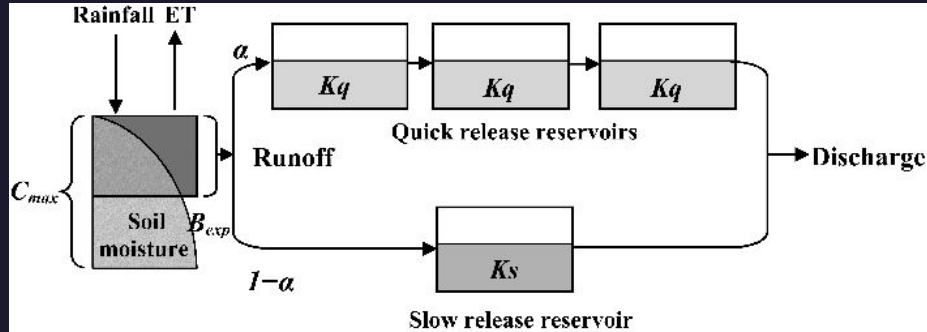
A tale of two experiments: (1) The Plumber Experiments



Best, Martin J., et al. "The plumbing of land surface models: benchmarking model performance." *Journal of Hydrometeorology* 16.3 (2015): 1425-1442.

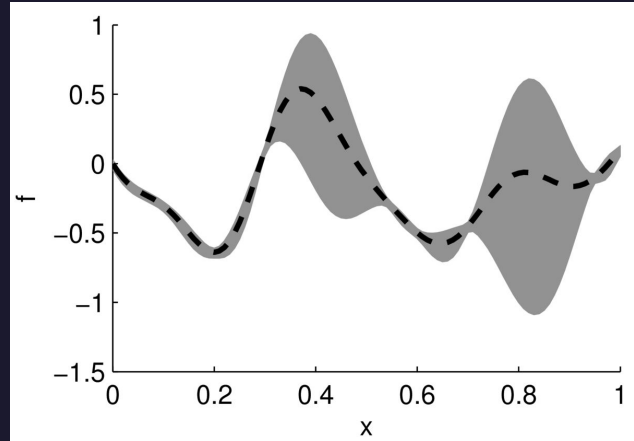
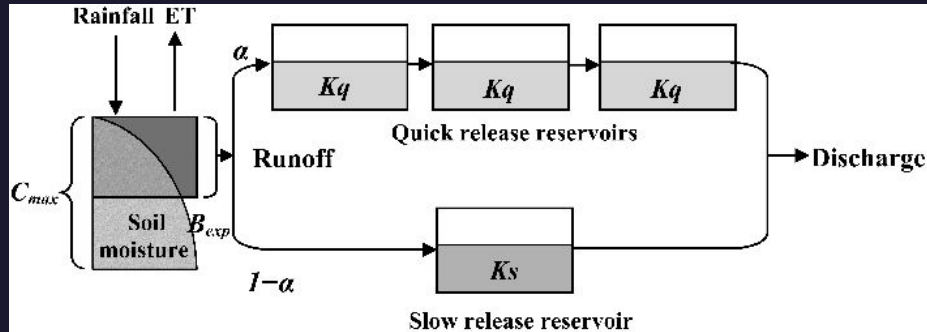
A tale of two experiments:

(2) State-Space Learning



$$\frac{dX}{dt} = f(X, u, \theta)$$

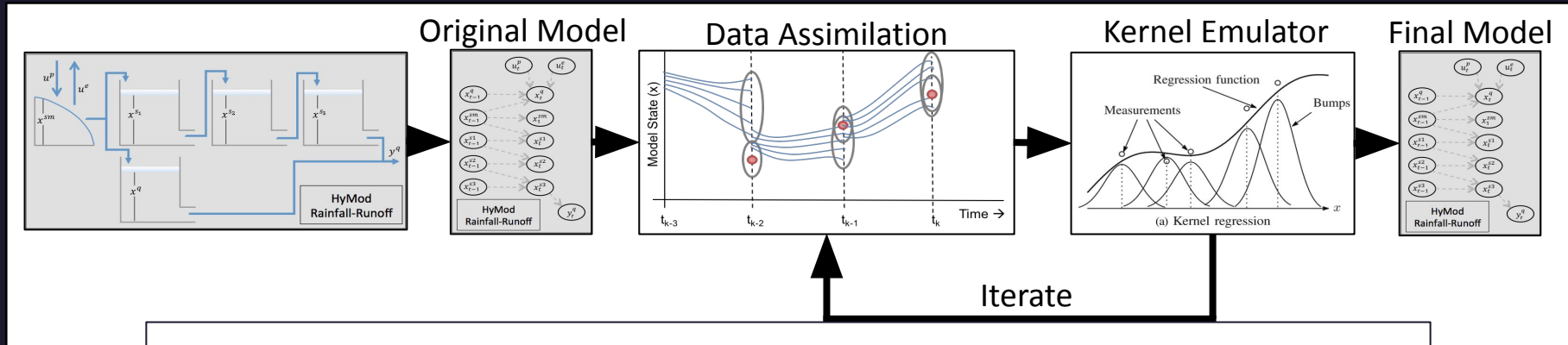
A tale of two experiments: (2) State-Space Learning



$$\frac{dX}{dt} = f(X, u, \theta)$$

$$+ g(X, u, \theta)$$

A tale of two experiments: (2) State-Space Learning

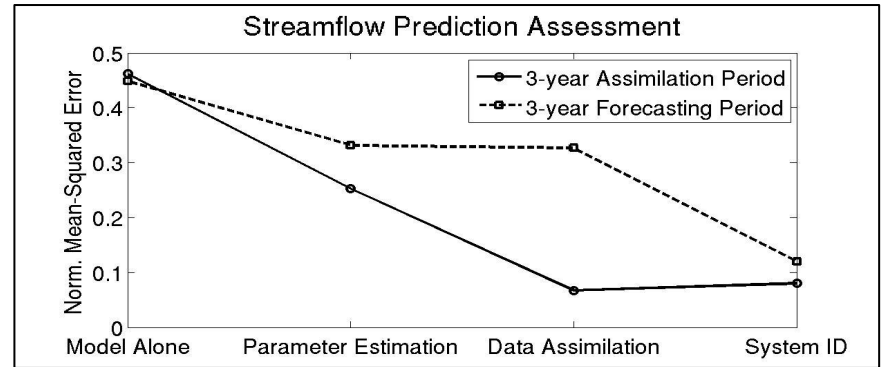
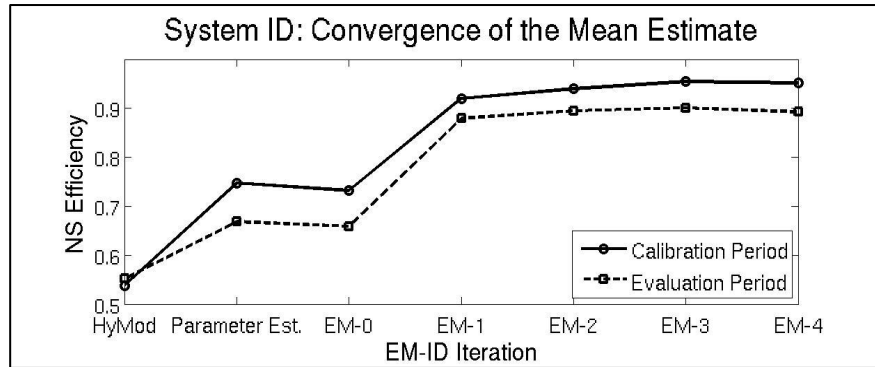


Expectation-Maximization Data Assimilation



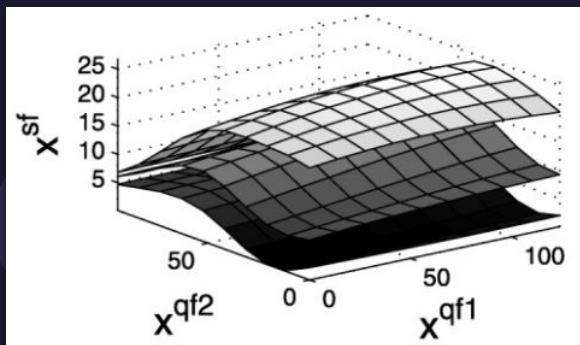
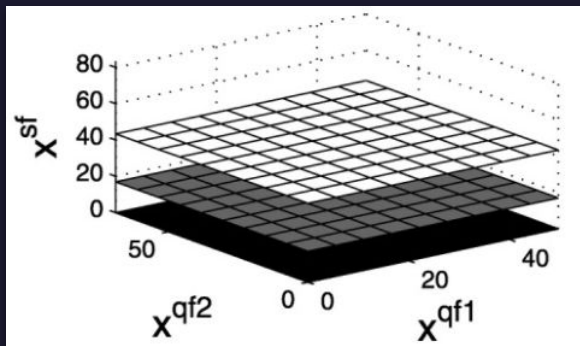
A tale of two experiments: (2) State-Space Learning

HyMod: Calibration, Assimilation, and System Identification



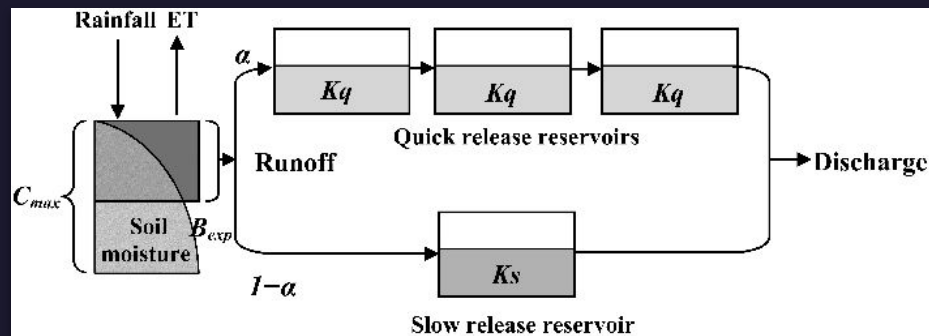
Nearing, Grey S., and Hoshin V. Gupta. "The quantity and quality of information in hydrologic models." *Water Resources Research* 51.1 (2015): 524-538.

A tale of two experiments: (2) State-Space Learning



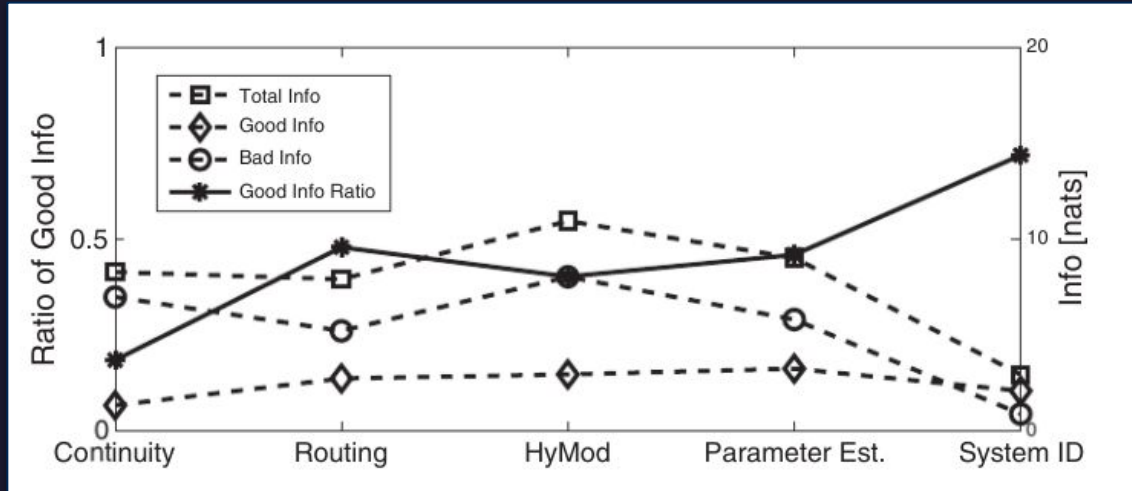
before ML

original model



after ML

A tale of two experiments: (2) State-Space Learning



Nearing, Grey S., and Hoshin V. Gupta. "The quantity and quality of information in hydrologic models." *Water Resources Research* 51.1 (2015): 524-538.

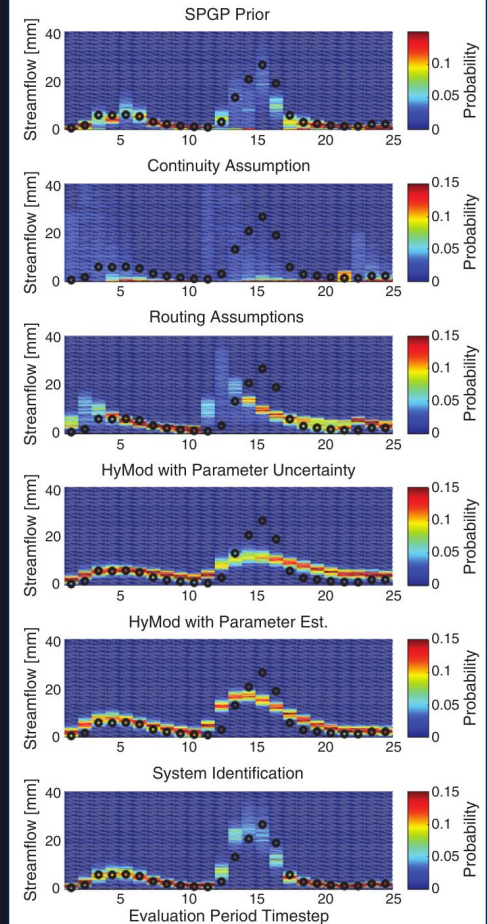
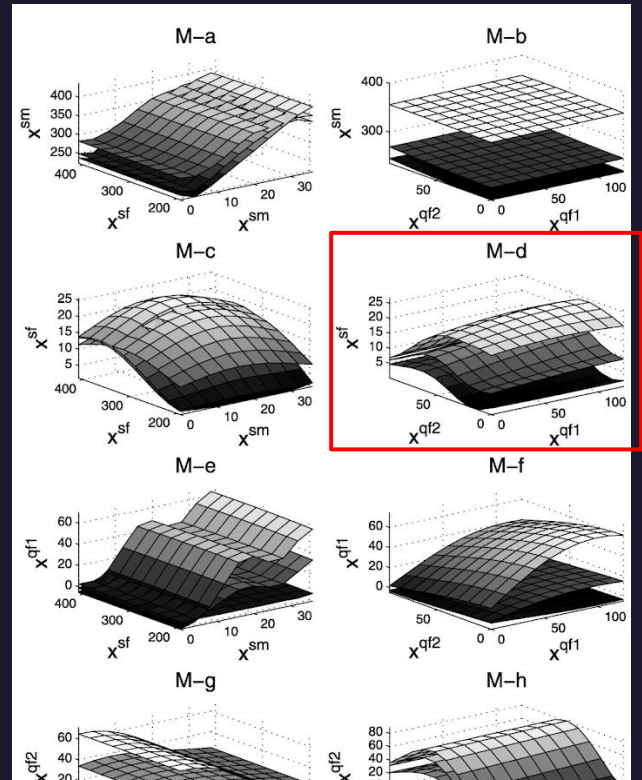
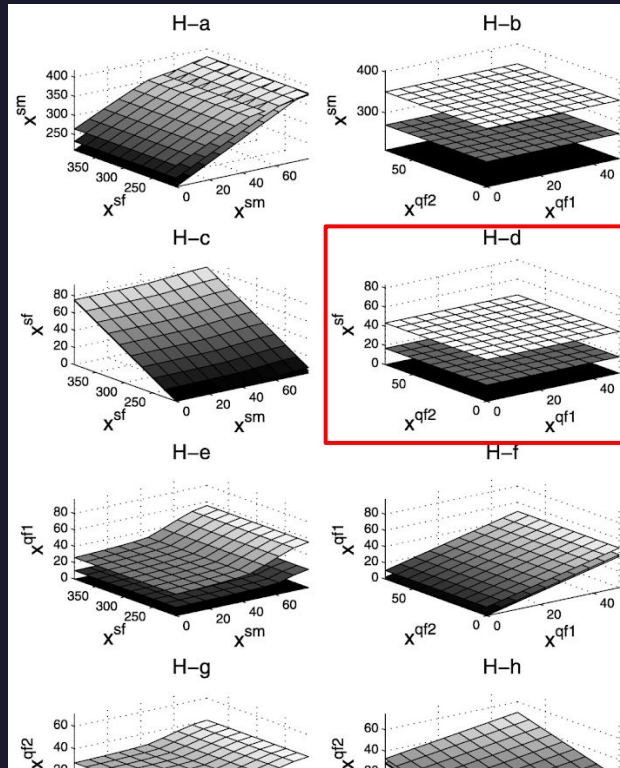


Figure 3. Evaluation period predictions of daily streamflow made by the empirical SGPR prior and each of the five inductive models. Black circles mark daily streamflow observations.

A tale of two experiments: (2) State-Space Learning

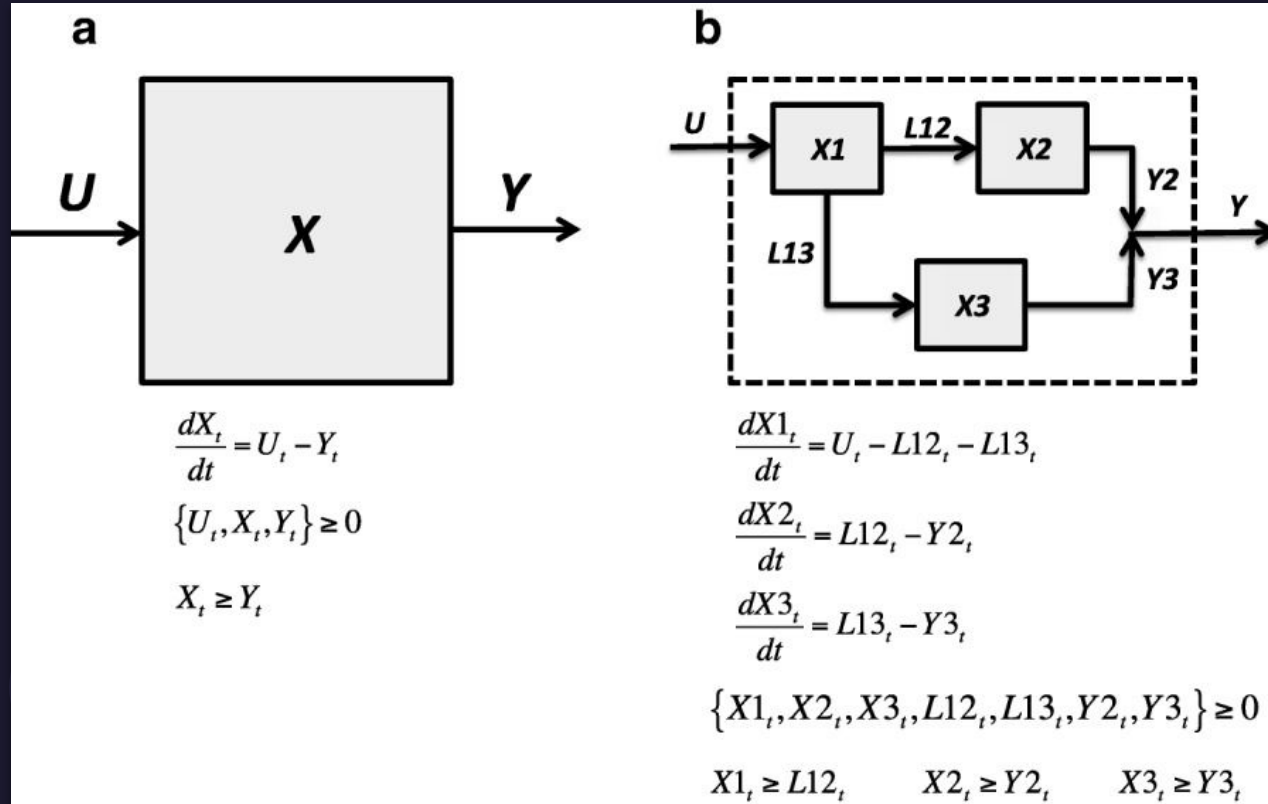


Which experiment is more interesting?

- (1) ML finds extra information in data
- (2) ML finds specific errors in a model



What is a model?



Gupta, Hoshin V., and Grey S. Nearing. "Debates—The future of hydrological sciences: A (common) path forward? Using models and data to learn: A systems theoretic perspective on the future of hydrological science." (2014).

What is a model?

Nearing, Grey S., and Hoshin V. Gupta. "Ensembles vs. information theory: supporting science under uncertainty." *Frontiers of Earth Science* (2018).

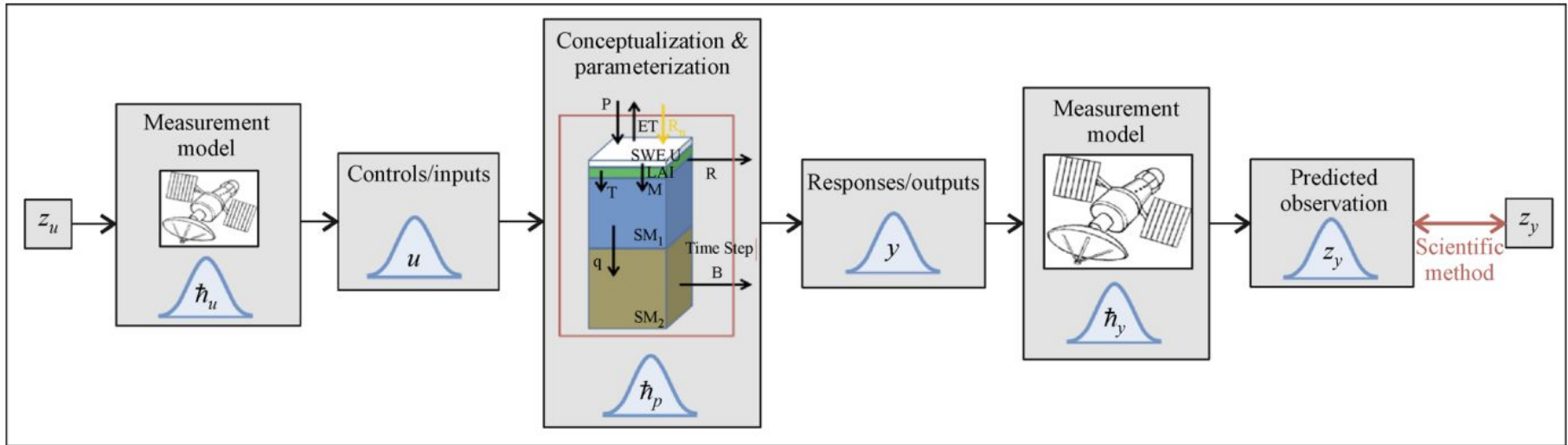
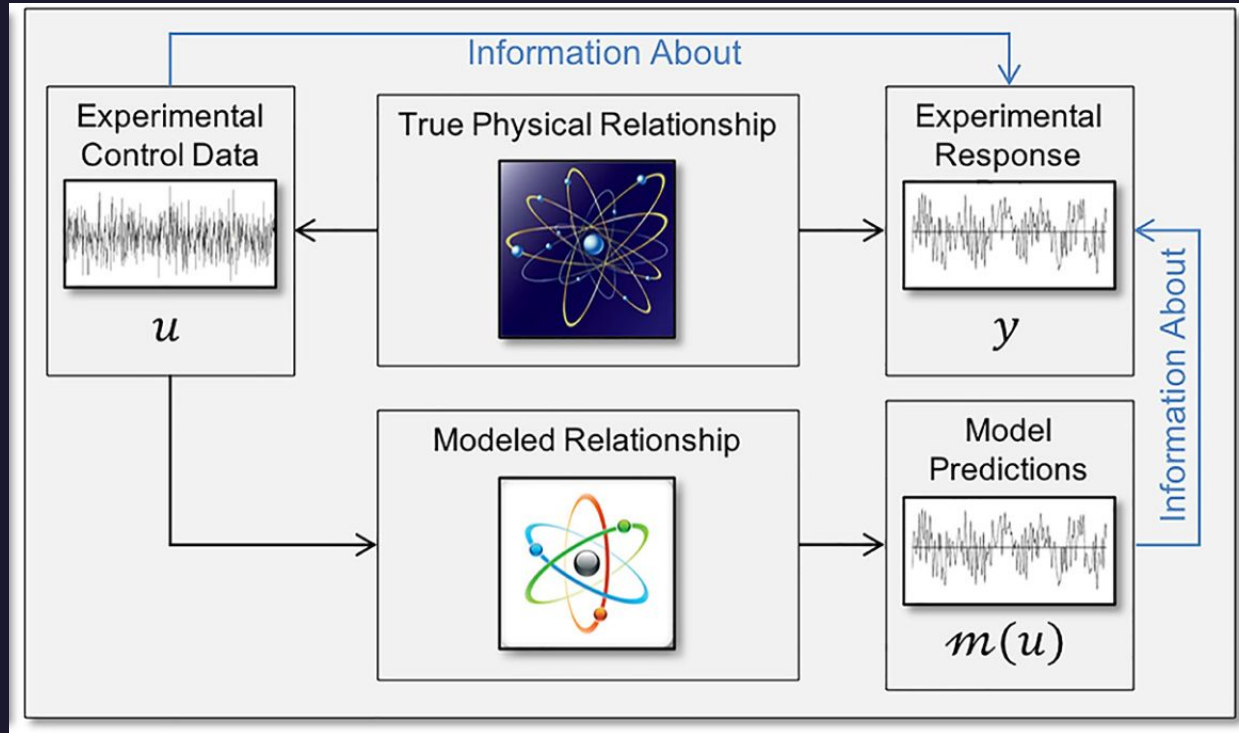


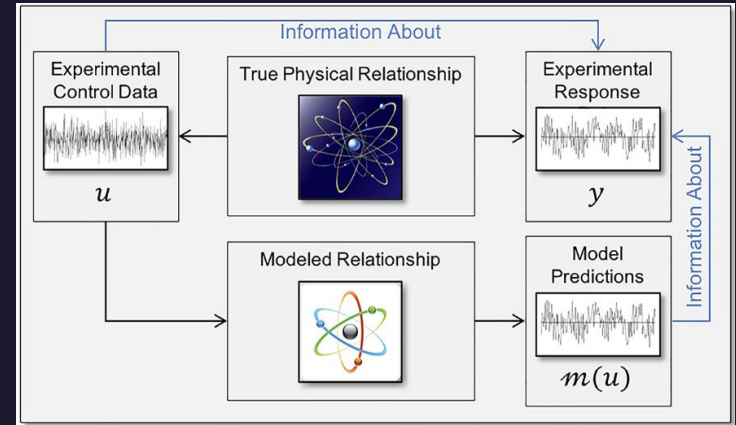
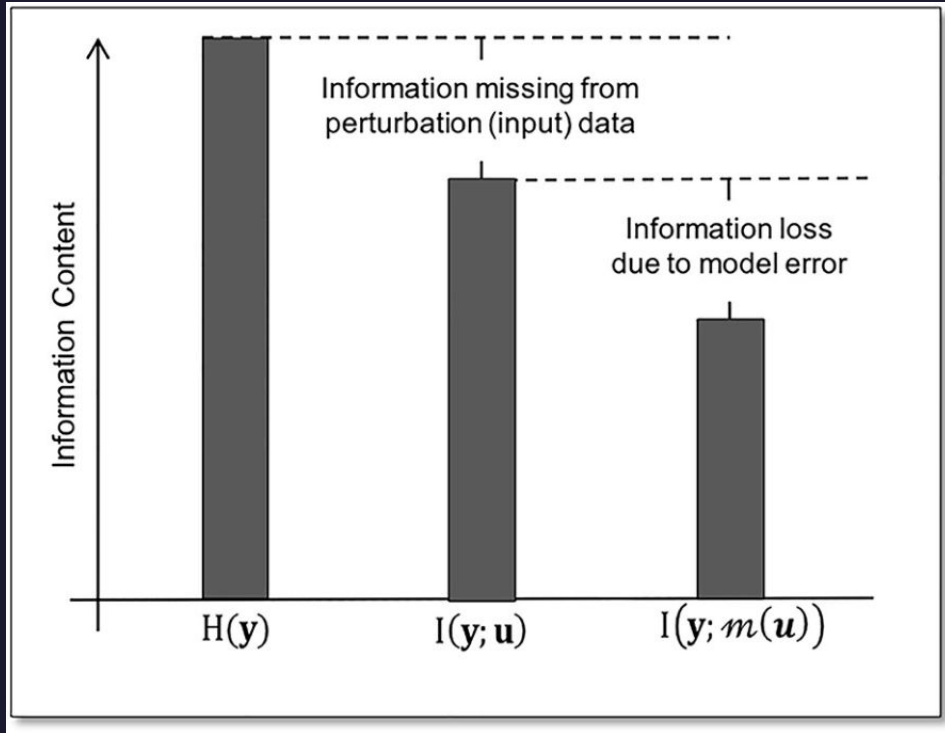
Fig. 1 Diagram of a simple experiment with a single input and single output. Even in the simplest case, we require at least one process hypothesis \hat{h}_p , and at least two measurement models \hat{h}_u and \hat{h}_y . Aleatory uncertainty is defined as the (unknown) distribution $\mathcal{J}(z_y|z_u)$, which would only be knowable if we had access to both a perfect process model and also perfect measurement models. A full model is the conjunction $\hat{h} = \{\hat{h}_p, \hat{h}_u, \hat{h}_y\}$.

What is hypothesis testing?



Nearing, Grey S., et al. "Does information theory provide a new paradigm for earth science? Hypothesis testing." *Water Resources Research* (2020).

What is hypothesis testing?



Gong, Wei, et al. "Estimating epistemic and aleatory uncertainties during hydrologic modeling: An information theoretic approach." *Water resources research* (2013).

What is a model?

Nearing, Grey S., and Hoshin V. Gupta. "Ensembles vs. information theory: supporting science under uncertainty." *Frontiers of Earth Science* (2018).

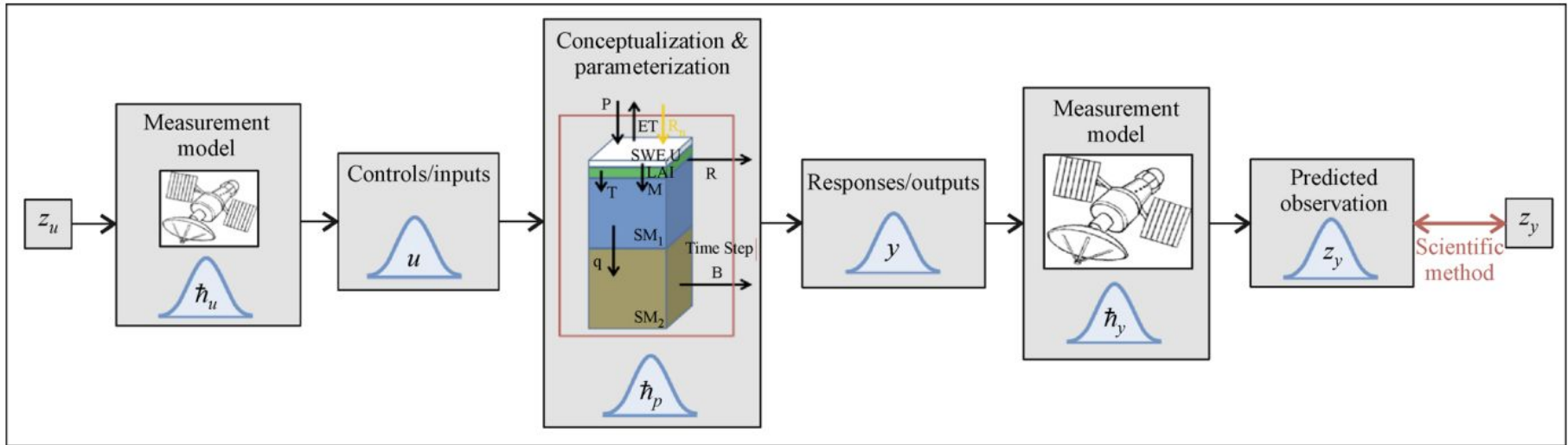
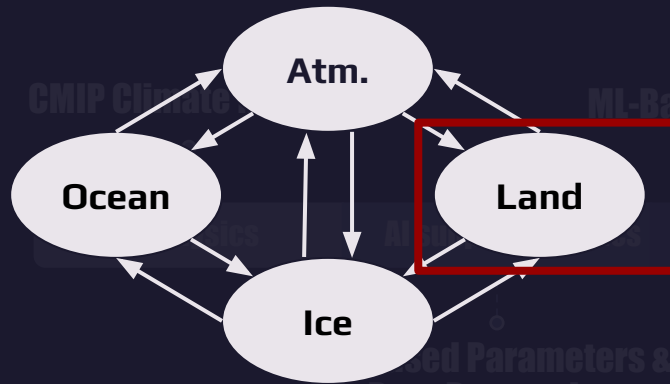


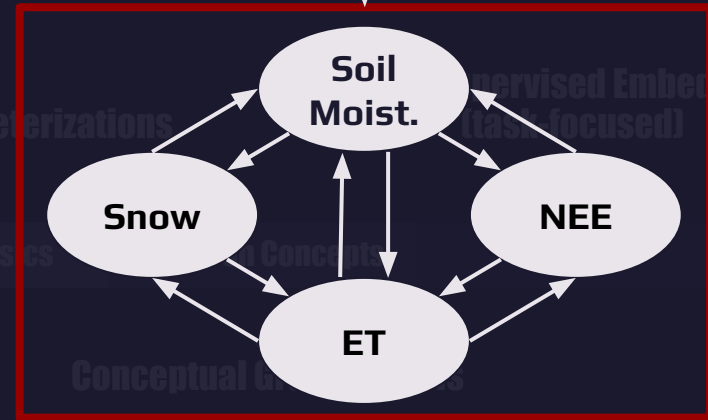
Fig. 1 Diagram of a simple experiment with a single input and single output. Even in the simplest case, we require at least one process hypothesis \hat{h}_p , and at least two measurement models \hat{h}_u and \hat{h}_y . Aleatory uncertainty is defined as the (unknown) distribution $\mathcal{J}(z_y|z_u)$, which would only be knowable if we had access to both a perfect process model and also perfect measurement models. A full model is the conjunction $\hat{h} = \{\hat{h}_p, \hat{h}_u, \hat{h}_y\}$.

Hierarchical Graph Models

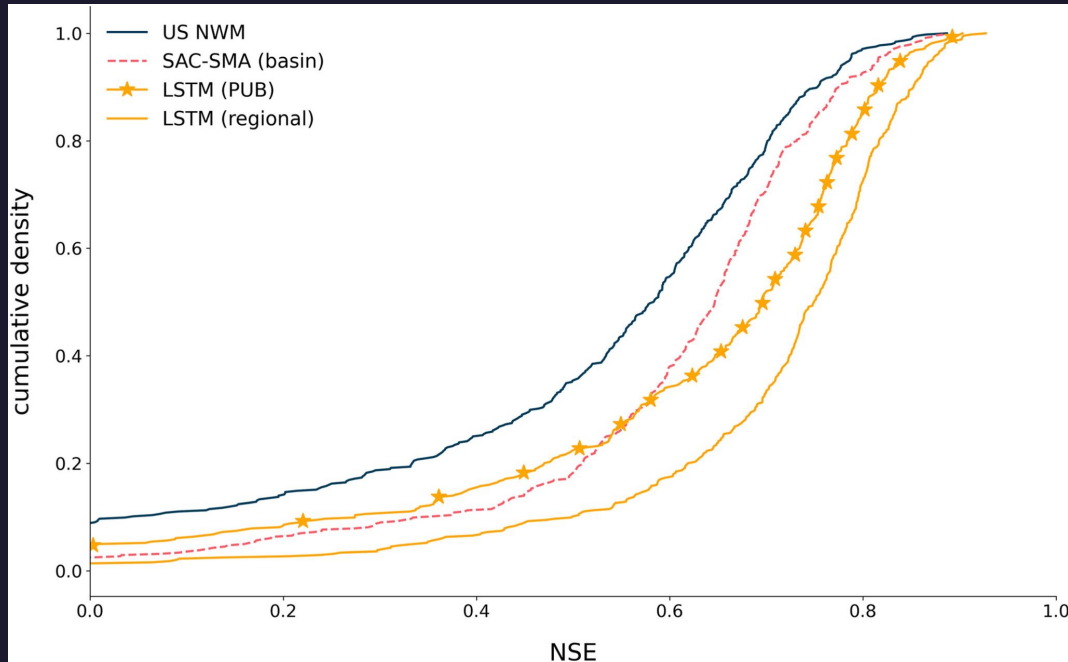
Climate Model



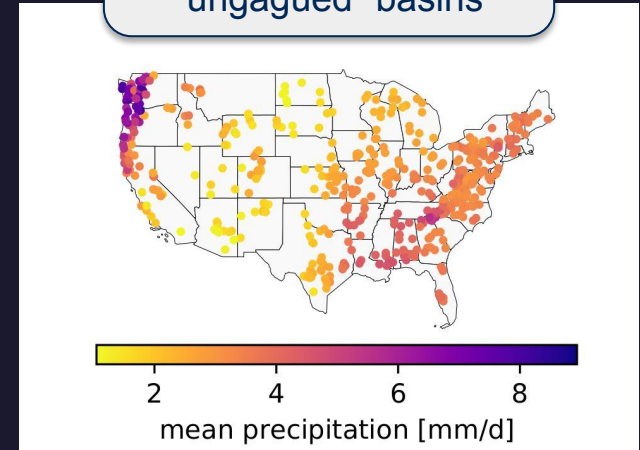
Forcings & Attributes



Finding new information *is* interesting



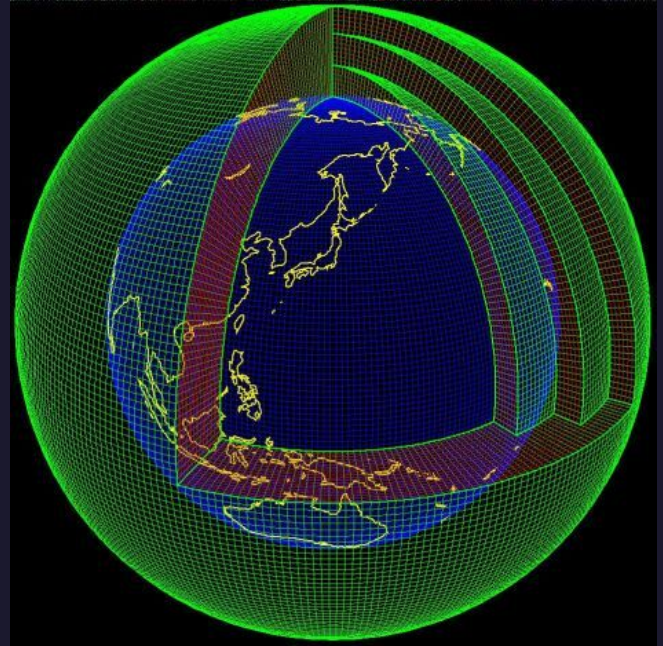
Space/time split
validation: tested in
“ungauged” basins



Kratzert, Frederik, et al. "Toward improved predictions in ungauged basins: Exploiting the power of machine learning." *Water Resources Research* 55.12 (2019).

Data + Domain Science Anecdotes

“Show that precipitation is useful for predicting floods.”



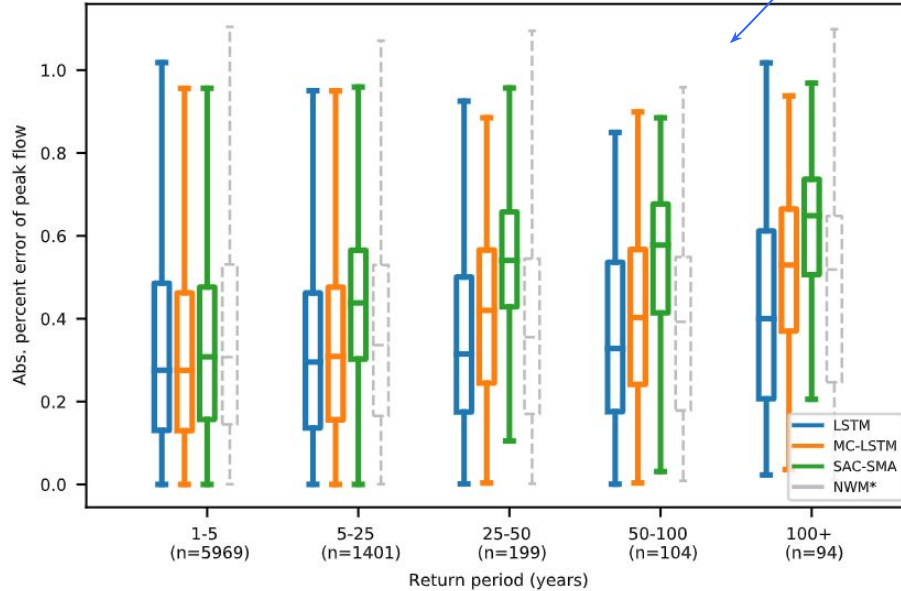
Data + Domain Science Anecdotes

Despite the impressive performance of ML models [for streamflow prediction] ... they have not been widely adopted by government agencies and practitioners ...

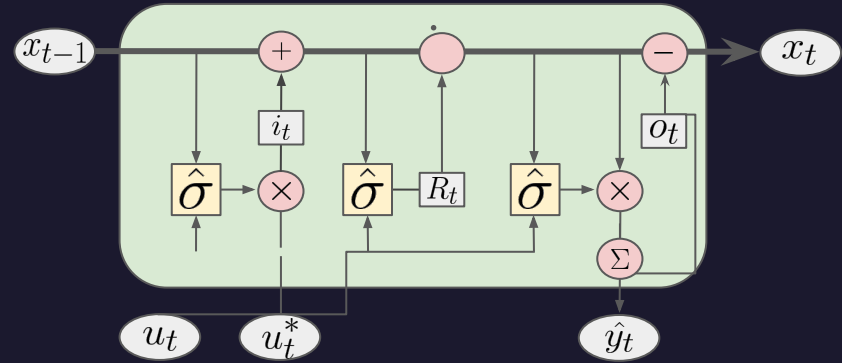
*While this is due in part to the AI community's failure to engage with the hydrologic community, [collaborative efforts are emerging] **leading to the integration of process knowledge with AI technologies.***

– Unnamed Hydrology Research Group

Mass Balance

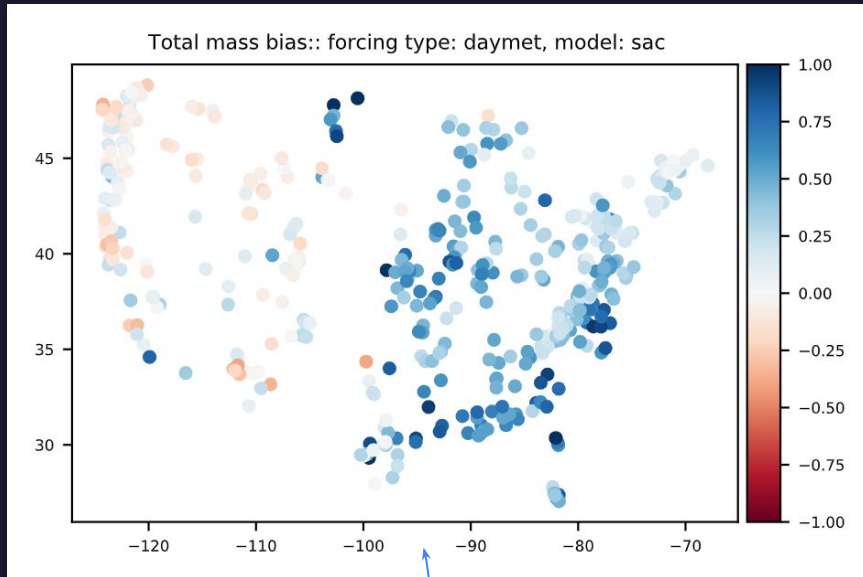


Adding a mass balance constraint does not improve even out-of-sample predictions.

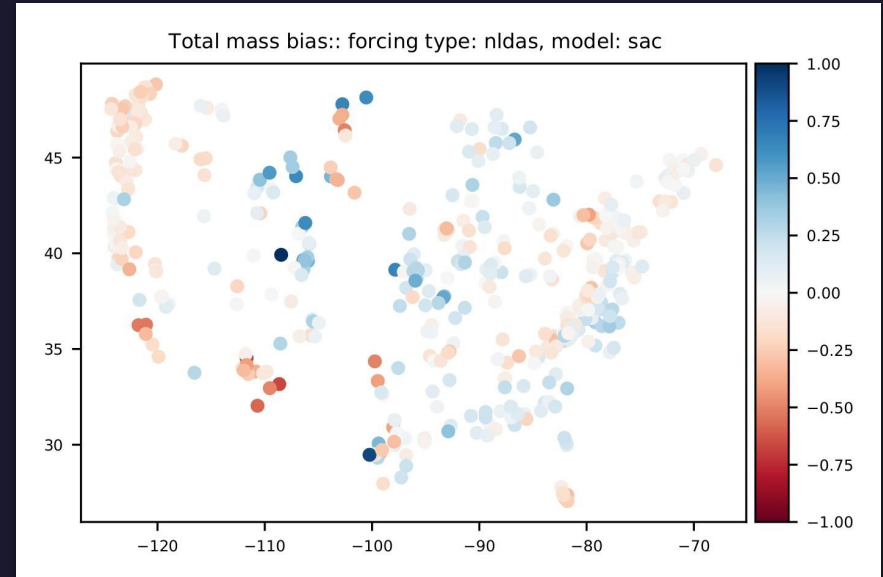


Mass Balance

DayMet Precipitation



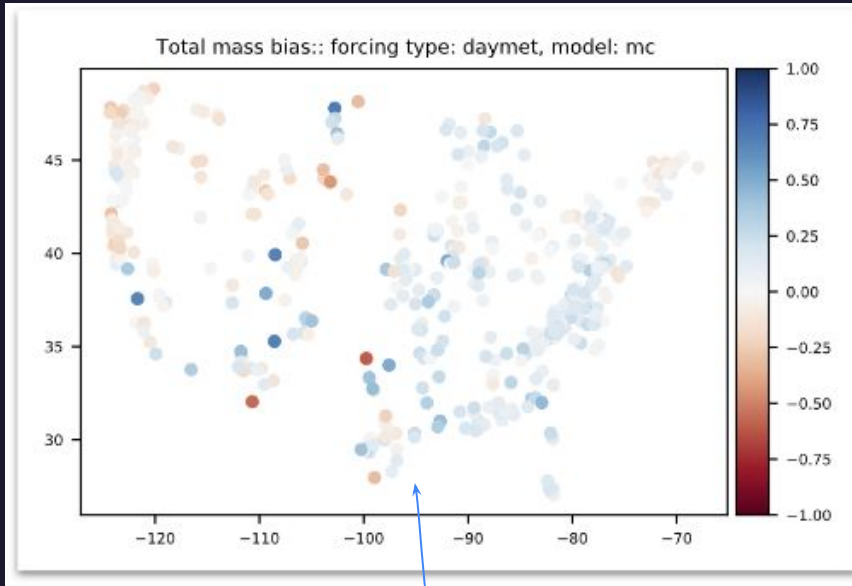
NLDAS Precipitation



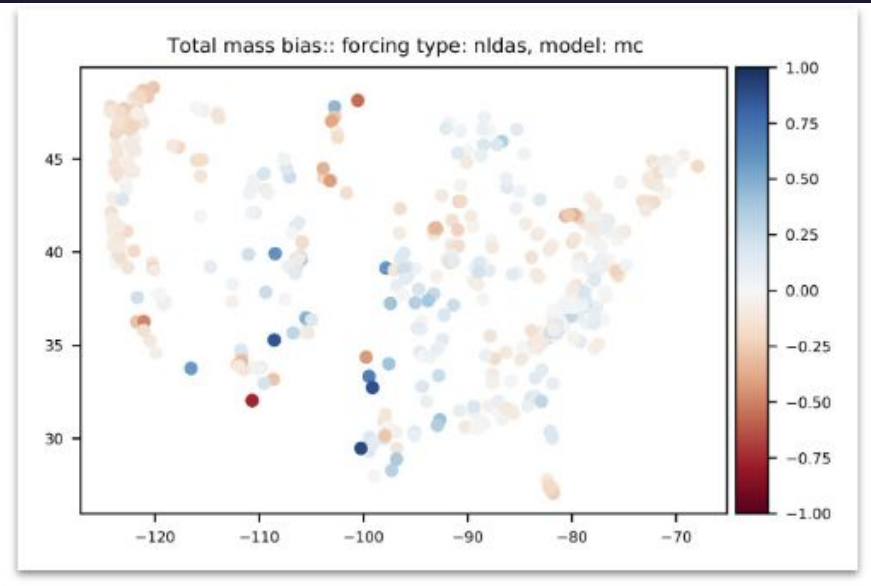
long-term bias in
traditional hydrology
model

Mass Balance

DayMet Precipitation



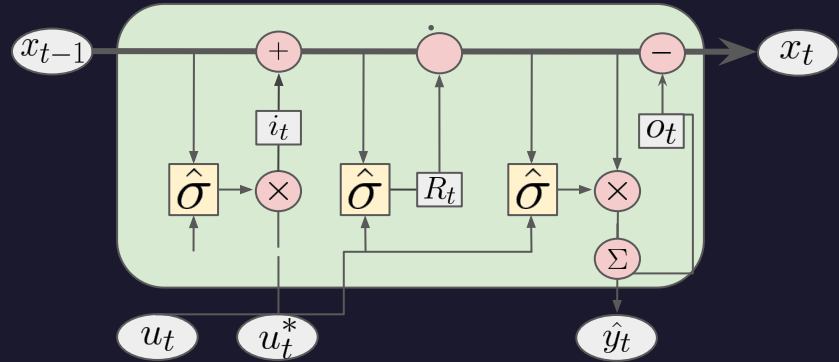
NLDAS Precipitation



Long-term bias is not present in
ML predictions.

Adding physics into ML streamflow models ... does not help (so far)

- Use physical models as inputs to ML models
- Add physical symmetries to ML model structures
- Regularize loss function
- Augmented / synthetic targets



“Isomorphisms” between physics and ML

“Building Blocks” of Physical Intuition:

- Spatial
 - Locality
 - Non-locality
 - Monotonicity
 - Causality
 - Symmetry (conservation)
 - Generalizability
- 
- A series of hand-drawn colored arrows connects the physical building blocks on the left to the ML types of inductive bias on the right. The arrows are: a red arrow from 'Locality' to 'Convolution (spatial & temporal)'; a green arrow from 'Non-locality' to 'Attention'; a blue arrow from 'Monotonicity' to 'Signed Activations'; a yellow arrow from 'Causality' to 'Networks'; a purple arrow from 'Symmetry (conservation)' to 'Regularization & Scaling'; and a white arrow from 'Generalizability' to 'Transfer Learning, Few Shot Learning, etc.'.

Types of Inductive Bias

- Convolution (spatial & temporal)
- Recurrence (temporal)
- Attention
- Signed Activations
- Networks
- Regularization & Scaling
- Transfer Learning, Few Shot Learning, etc.

What are the core challenges?

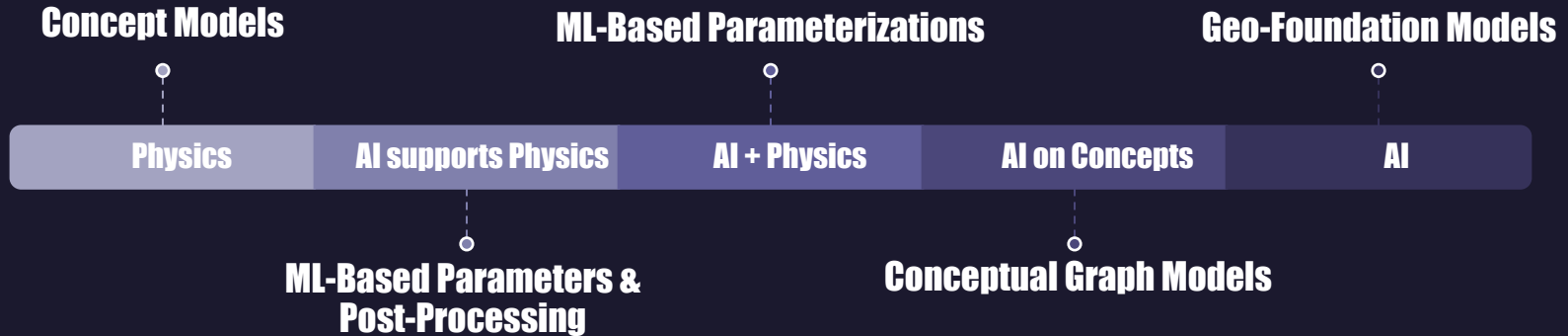


What are the core challenges?

- (1) Can physics constrain imperfect optimization?
- (2) Can physics regularize outside of the training envelope?

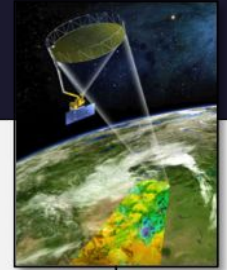
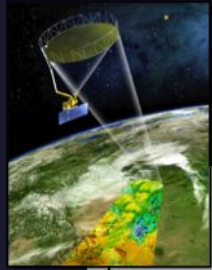


Where is data-based Geoscience modeling headed?



What is a model?

Nearing, Grey S., and Hoshin V. Gupta. "Ensembles vs. information theory: supporting science under uncertainty." *Frontiers of Earth Science* (2018).



$$p(z_y|z_\theta, z_u) = \int \int p(z_y|y, h_y) p(y|u, \theta, h_s) p(u|z_u, h_u) p(\theta|z_\theta, h_\theta) d_{u,\theta,y} \mu_{h_s, h_u, h_\theta, h_y}$$

