## Finite and Infinite Models: Optimal Prediction of Hidden Markov Proceses



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Information Theory as a Bridge Across the Geosciences and Modeling Sciences

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## review article

## Simple mathematical models with very complicated dynamics

Robert M. May*

First-order difference equations arise in many contexts in the biological, economic and social sciences. Such equations, even though simple and deterministic, can exhibit a surprising array of dynamical behaviour, from stable points, to a bifurcating hierarchy of stable cycles, to apparently random fluctuations. There are consequently many fascinating problems, some concerned with delicate mathematical aspects of the fine structure of the trajectories, and some concerned with the practical implications and applications. This is an interpretive review of them.

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## Object of Study: Processes



The random variables $X_{i}$ may take on values in alphabet $A$ :

$$
\overleftrightarrow{X}=\ldots X_{-1} X_{0} X_{1} \ldots
$$

## Object of Study: Processes



Let $A=\{0,1\}$. Then a realization of the process is written

$$
\begin{aligned}
\overleftrightarrow{x} & =\ldots x_{-1} x_{0} x_{1} \ldots \\
& =\ldots 011 \ldots
\end{aligned}
$$

System Instrument Process
A process $P$ is defined as the probability distribution over bi-infinite strings.

## Information Theory



The Shannon entropy over a random variable is defined:

$$
H[X]=-\sum_{x \in A} \operatorname{Pr}(X=x) \log _{2} \operatorname{Pr}(X=x)
$$

## Information Theory



## Information Theory

$$
\overleftrightarrow{X}=\ldots X_{-3} X_{-2} X_{-1} X_{0} X_{1} X_{2} X_{3} \ldots
$$

$H\left[X_{0}\right]$



## Entropy Rate

$$
\begin{aligned}
h_{\mu} & =\lim _{L \rightarrow \infty} H\left[X_{0} \mid \text { Past }\right] \\
& =\lim _{L \rightarrow \infty}\left(H\left[X_{0}, \text { Past }\right]-H[\text { Past }]\right)
\end{aligned}
$$

$h_{\mu}$ is the irreducible randomness of a process.


This is the limit of our predictive abilities.

## Excess Entropy



## Elusive Information



## Models of Time Series



## Models of Time Series



## Models of Time Series



## Models of Time Series



## Models of Time Series



## Hidden Markov Models



## The Utility of (Good) Models



$$
h_{\mu}=\sum_{\sigma \in S} \operatorname{Pr}(\sigma) H[X \mid \sigma]
$$

## The Utility of (Good) Models



## What's "Good"?



## $\epsilon$-Machines are "Good"



- States are a function of the past
- Optimal predictor
- Minimal in size
- Unique
$\Rightarrow$ The $\epsilon$ machine


## $\epsilon$-Machines are "Good"



- States are a function of the past
- Optimal predictor
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$\Rightarrow$ The $\epsilon$ machine
Mechanism?


## $\epsilon$-Machines are "Good"



The number of bits required to store the $\epsilon$ -machine is called the statistical complexity:

$$
C_{\mu}=H[\mathrm{~S}]
$$

## Most HMMs are Not Optimal Predictors!



$$
h_{\mu} \neq \sum_{\sigma \in \mathrm{S}} \operatorname{Pr}(\sigma) H[X \mid \sigma]
$$

## Problem Statement

Given an arbitrary finite-state hidden Markov model,
how to get $\epsilon$-machine?

## Observe and Update Game



Observed sequence: $\lambda$

## Observe and Update Game



Observed sequence: $\lambda 1$

## Observe and Update Game



Observed sequence: $\lambda 10$

## Observe and Update Game



Observed sequence: $\lambda 101$

## Observe and Update Game



Observed sequence: $\lambda 1011$

## Observe and Update Game




## The Infinite State $\epsilon$-Machine



The set of belief states $R$ is the attractor of the<br>"observe and update" stochastic dynamical<br>system (known as an iterated function system).

## The Infinite State $\epsilon$-Machine


$\operatorname{Pr}(0,0,1)$

The set of belief states $R$ is the attractor of the
"observe and update" stochastic dynamical
system (known as an iterated function system).
This attractor exists and is unique due to contractivity, but is generically fractal-like.

## The Infinite State $\epsilon$-Machine



For most finitely generated hidden Markov
processes, the $\epsilon$ machine is an uncountably
infinite state set + transitions between these
states.

## Calculating Shannon Entropy Rate



## Calculating Shannon Entropy Rate



$$
h_{\mu}^{B}=\int_{R} \mathrm{~d} \mu(\eta) H[X \mid \eta]
$$

## Calculating Shannon Entropy Rate


$\mu(R)$ is called the Blackwell measure.
It can be used to calculate the entropy rate:

$$
\begin{aligned}
& h_{\mu}^{B}=\int_{R} \mathrm{~d} \mu(\eta) H[X \mid \eta] \\
& \widehat{h_{\mu}^{B}}=\lim _{L \rightarrow \infty} \frac{1}{L} \sum_{t=0}^{L} H\left[X_{t} \mid \eta_{t}\right]
\end{aligned}
$$

## Structure: Statistical Complexity?

$$
C_{\mu} \rightarrow \infty
$$

## Structure: Information Dimension



## Statistical Complexity Dimension?



$$
\begin{gathered}
C_{\mu} \rightarrow \infty \\
\operatorname{dim}_{\mu}(R) \sim \frac{\Delta H\left[R_{\epsilon}\right]}{\Delta \ln \epsilon}=\frac{\Delta C_{\mu, \epsilon}}{\Delta \ln \epsilon}
\end{gathered}
$$

## Calculating Information Dimension

Calculate the Lyapunov spectrum:

$$
\begin{aligned}
& \Gamma=\left\{\lambda_{1}, \lambda_{2}, \ldots, \lambda_{N}\right\} \\
& \quad \text { s.t. } \lambda_{1} \geq \lambda_{2} \geq \ldots \geq \lambda_{N}
\end{aligned}
$$

Kaplan-Yorke conjecture:

$$
\operatorname{dim}_{I}=k+\frac{\sum_{i}^{k} \lambda_{i}}{\left|\lambda_{k+1}\right|}
$$

Where $k$ is the largest index for which the sum

$$
\sum_{i}^{k} \lambda_{i} \text { is positive. }
$$

# Calculating Information Dimension 

For the Lorenz attractor with $\sigma=10, r=28$,
$b=8 / 3$ :

$$
\Gamma=\{0.90563,0,-14.57219\}
$$

So the Lyapunov dimension is:

$$
\operatorname{dim}_{I}=2.06215
$$

## New Quantity: The Ambiguity Rate

Entropy rate measures uncertainty in the next symbol given the present.

$$
h_{\mu}=H\left[X_{0}, S_{1} \mid S_{0}\right]
$$



## New Quantity: The Ambiguity Rate



Entropy rate measures uncertainty in the next symbol given the present.

$$
h_{\mu}=H\left[X_{0}, S_{1} \mid S_{0}\right]
$$

Ambiguity rate measures uncertainty in prior symbol given the present.

$$
h_{a}=H\left[X_{-1}, \mathrm{~S}_{-1} \mid \mathrm{S}_{0}\right]
$$

## Statistical Complexity Dimension



$$
\operatorname{dim}_{\mu}(R)=k+\frac{h_{\mu}-h_{a}+\sum_{i}^{k} \lambda_{i}}{\left|\lambda_{k+1}\right|}
$$

## Statistical Complexity Dimension



Alexandra M. Jurgens, James P. Crutchfield. Divergent Predictive Memory: The Statistical Complexity Dimension of Stationary, Ergodic Finite-State Hidden Markov Processes. Chaos 31, 083114, 2021.
Alexandra M. Jurgens, James P. Crutchfield. Ambiguity rate of hidden Markov processes. Phys. Rev. E, 104 (2021)

## Statistical Complexity Dimension



$$
\begin{gathered}
C_{\mu} \rightarrow \infty \\
\operatorname{dim}_{\mu}(R)=\frac{\Delta C_{\mu, \epsilon}}{\Delta \ln \epsilon}=k+\frac{h_{\mu}-h_{a}+\sum_{i}^{k} \lambda_{i}}{\left|\lambda_{k+1}\right|}
\end{gathered}
$$

$\rightarrow$ Can calculate randomness and structure, now for infinite states!

## Growth Rate of Predictive Models

$\Delta H[$ Predictive states $]=h_{\mu}-h_{a}$


Entropy rate

Ambiguity rate

## Growth Rate of Predictive Models



For a finite state model:

$$
h_{\mu}-h_{a}=0
$$

## Growth Rate of Predictive Models

$$
\Delta H[\text { Predictive states }]=h_{\mu}-h_{a}
$$


"Every history counts"

$$
h_{\mu}-h_{a}=h_{\mu}
$$



## Growth Rate of Predictive Models

$$
\Delta H[\text { Predictive states }]=h_{\mu}-h_{a}
$$

Finite states

$$
h_{\mu}-h_{a}=0
$$



In general:

$$
h_{\mu}>h_{\mu}-h_{a}>0
$$


"Every history counts"

$$
h_{\mu}-h_{a}=h_{\mu}
$$



## Acknowledgements + Questions



Thank you to my PhD advisor, Jim Crutchfield, and all those at the Complexity Sciences Center, especially Alec Boyd, Adam Rupe, Sam Loomis and for helpful discussions.

Thank you as well to my curent group leader at INRIA Bordeaux, Nicolas Brodu.

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## Acknowledgements + Questions

Create tikz code depicting an iceberg, but overlay a finite state machine on the above water portion and a black rectangle on the underwater portion. Include code to replace the rectangle by an inserted image.

Certainly! Below is the TikZ code to depict an iceberg with a finite state machine (FSM) overlay on the above water portion and a black rectangle on the underwater portion. Additionally, it includes the code to replace the black rectangle with an inserted image.


Thank you to my PhD advisor, Jim Crutchfield, and all those at the Complexity Sciences Center, especially Alec Boyd, Adam Rupe, Sam Loomis and for helpful discussions.

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## The Utility of (Good) Models



$$
\begin{gathered}
h_{\mu}=\sum_{\sigma \in \mathrm{S}} \operatorname{Pr}(\sigma) H[X \mid \sigma] \\
E=I[\overrightarrow{\mathrm{~s}} ; \overleftarrow{\mathrm{s}}] \\
\sigma_{\mu}=I\left[\overrightarrow{\mathrm{~S}} ; \overleftarrow{\mathrm{S}} \mid X_{0}\right]
\end{gathered}
$$

## The Utility of (Good) Models



Ryan G. James, Christopher J. Ellison, James P. Crutchfield. Anatomy of a bit: Information in a time series observation. Chaos 21, 037109 (2011)

